Simple Harmonic Motion

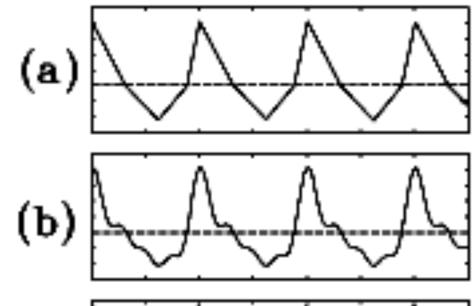
Many types of time-dependence are **periodic**,

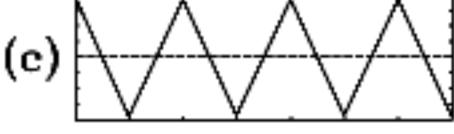
but only one type is "harmonic",

namely,

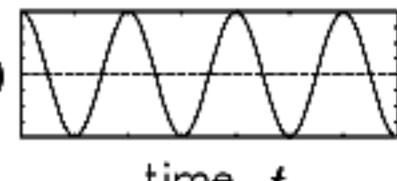
sinusoidal motion. —— (e)

What are its properties?









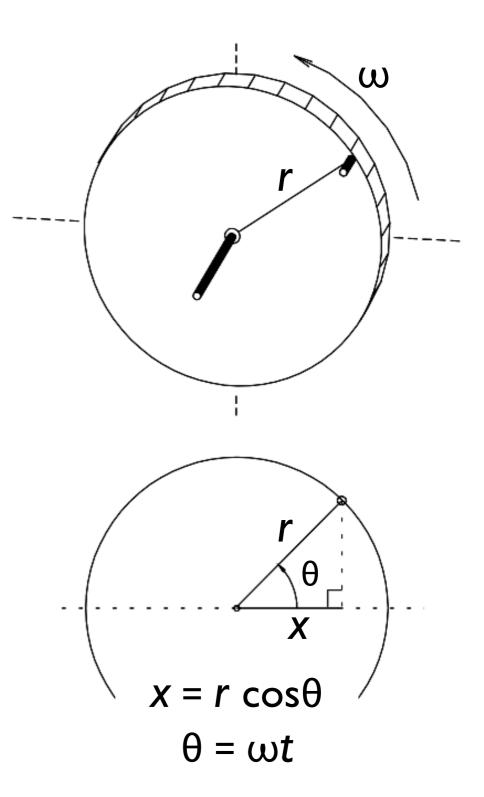
time t

Projecting the Wheel

Picture a wheel spinning at constant angular velocity ω.

Now picture the motion of the **shadow** of a **pin** on the rim of the wheel (at high noon on the Equator).

This is called (reasonably) the **projected** motion of the pin.



A Little Mathematics:

For
$$\theta \ll 1$$
, $\cos(\theta) \approx 1 - \frac{1}{2}\theta^2$
and $\sin(\theta) \approx \theta$.

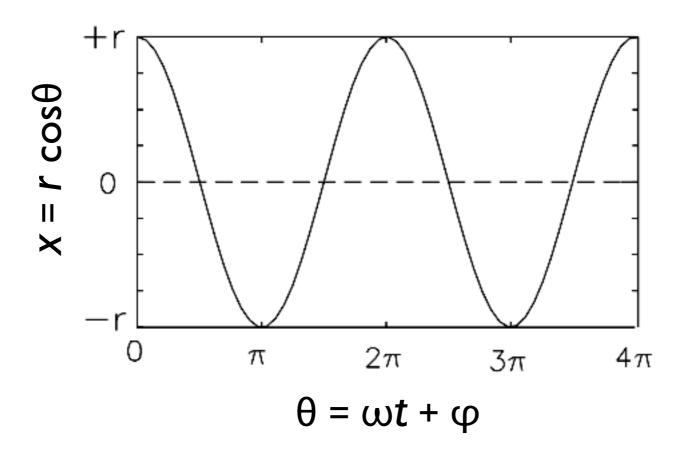
Taylor Series Expansions for Exponential & Sinusoidal Functions:

$$\exp(z) = 1 + z + \frac{1}{2}z^2 + \frac{1}{3!}z^3 + \frac{1}{4!}z^4 + \cdots$$

$$\cos(z) = 1$$
 $-\frac{1}{2}z^2$ $+\frac{1}{4!}z^4$ $-\cdots$

$$\sin(z) = z \qquad -\frac{1}{3!}z^3 \qquad + \cdots$$

Derivatives of the Cosine Function



$$x = r \cos(\omega t + \varphi)$$

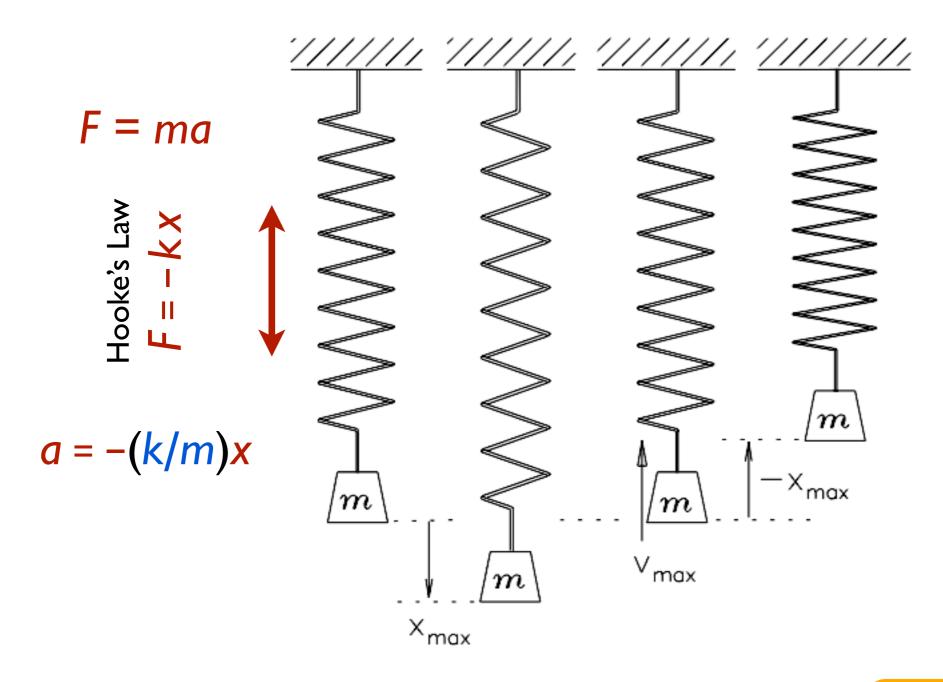
Note:

$$v = dx/dt = -\omega r \sin(\omega t + \varphi)$$

$$d^2x/dt^2 = -\omega^2 x$$

$$a = d^2x/dt^2 = -\omega^2 r \cos(\omega t + \varphi)$$

The Spring Pendulum



So
$$a = d^2x/dt^2 = -\omega^2x$$
 if $\omega^2 = k/m$ or

 $\omega = \sqrt{k/m}$

Our old friend, the Exponential:

Remember
$$dx/dt = -\kappa x \Leftrightarrow x(t) = x_0 \exp(-\kappa t)$$
?

The second derivative would be $\frac{d^2x}{dt^2} = \kappa^2 x$, right?

Well, now we have a new equation $\frac{d^2x}{dt^2} = -\omega^2 x$, which means the exponential function would be a solution if only we could have $\kappa^2 = -\omega^2$.

Of course this is impossible. No real number is negative when squared.

But what if there were such a number? Use your imagination! $i = \sqrt{-1}$

Then we could solve our differential equation in one step:

$$x(t) = x_0 \exp(i \omega t)$$
 — but what does this **mean**?

Complex Exponentials

Taylor Series Expansions for Exponential & Sinusoidal Functions:

$$\exp(z) = 1 + z + \frac{1}{2}z^2 + \frac{1}{3!}z^3 + \frac{1}{4!}z^4 + \cdots$$

Recall
$$\cos(z) = 1$$
 $-\frac{1}{2}z^2$ $+\frac{1}{4!}z^4$ $-\cdots$

What if
$$z = i\theta$$
?

$$\sin(z) =$$

$$\sin(z) = z \qquad -\frac{1}{3!}z^3 \qquad + \cdots$$

$$+\cdots$$

$$\exp(i\theta) = 1 + i\theta - \frac{1}{2!}\theta^2 - \frac{1}{3!}i\theta^3 + \frac{1}{4!}\theta^4 + \cdots$$

$$-\frac{1}{2}!\theta^{2}$$

$$-\frac{1}{3!}i\theta^{3}$$

$$+ \frac{1}{4} \cdot \theta^4$$

$$cos(\theta) = 1$$

$$-\frac{1}{2}!\theta^{2}$$

$$+ \frac{1}{4!}\theta^4 + \cdots$$

$$i \sin(\theta) =$$

$$i\theta$$

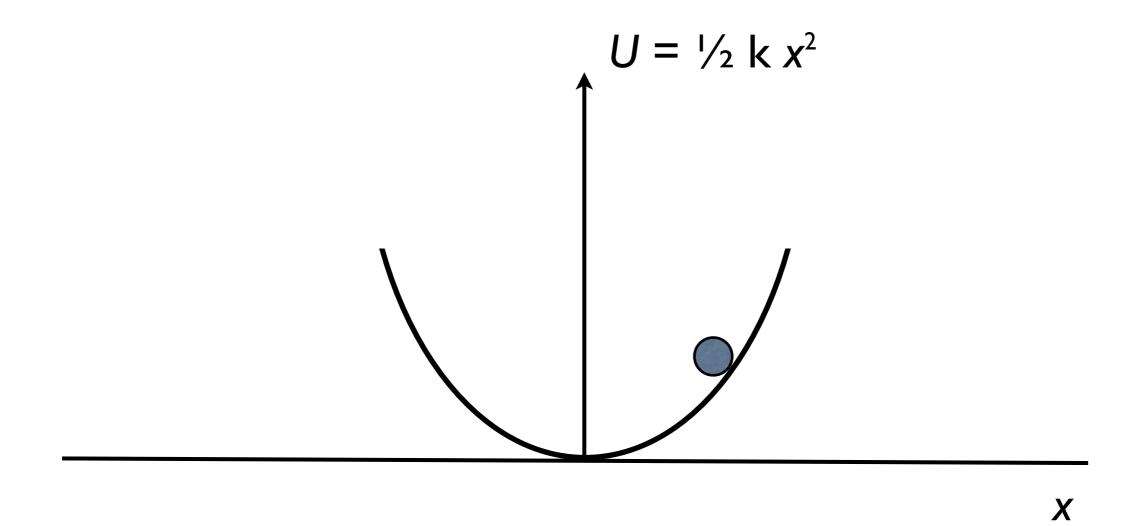
$$-\frac{1}{3!}i\theta^{3}$$

This means

$$e^{i\theta} = \cos\theta + i\sin\theta$$

Don't tell anyone I told you about this!

Quadratic Potential Minimum



F = -dU/dx = -kx

Simple Harmonic Motion

Linear Restoring Force (Hooke's Law)

$$F = -kx$$



Quadratic Potential Minimum

$$U = \frac{1}{2} k x^2$$

plus

Inertial Factor m



SHM

$$\frac{d^2x}{dt^2} = -\omega^2x$$

$$x = x_0 \cos(\omega t + \varphi)$$

$$\mathbf{v} = \frac{\mathrm{d}x}{\mathrm{d}t} = -\mathbf{w} x_0 \sin(\omega t + \varphi)$$

$$a \equiv \frac{d^2x}{dt^2} = -\omega^2 x_0 \cos(\omega t + \varphi)$$

$$\omega^2 = k/m$$

Damped Harmonic Motion:

Remember viscous damping?

$$d^2x/dt^2 = -\kappa dx/dt \iff v(t) = v_0 \exp(-\kappa t)$$

With a linear restoring force and viscous damping, the equation is

$$\frac{d^2x}{dt^2} = - \kappa \frac{dx}{dt} - \omega^2 x$$

which still might be satisfied by $x(t) = x_0 \exp(Kt)$ with some K.

Let's try! Plug this x(t) back into the equation, giving

$$K^2 x = -\kappa K x - \omega^2 x$$
 or $K^2 + \kappa K + \omega^2 = 0$

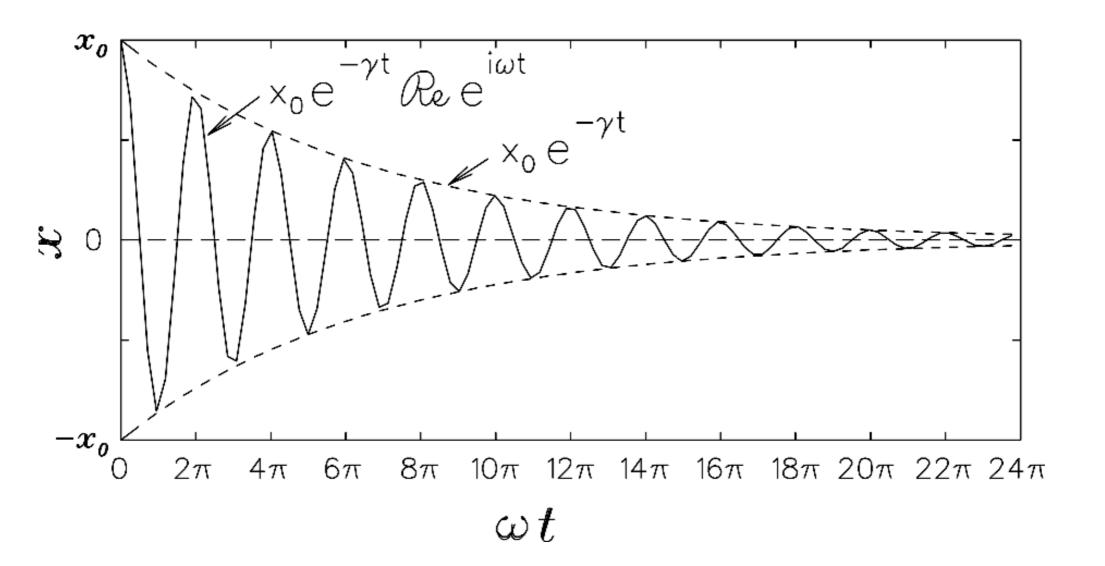
which has the solution
$$2K = -\kappa \pm \sqrt{\kappa^2 - 4\omega^2}$$

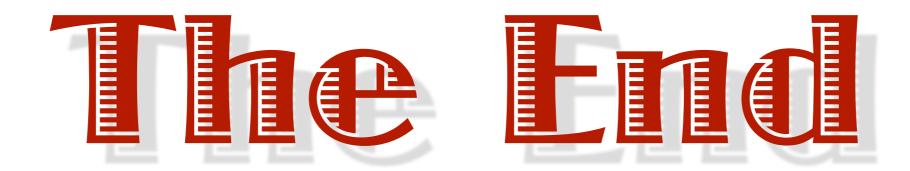
Again, what does this mean?

Damped Harmonic Motion:

If
$$2K = -\kappa \pm \sqrt{\kappa^2 - 4\omega^2}$$
 then
$$K = -\frac{1}{2}\kappa \pm i\omega\sqrt{1 - \frac{1}{4}\kappa^2/\omega^2}$$

$$x(t) = x_0 e^{-\frac{1}{2}K} \exp(\pm i \omega' t)$$
 where $\omega' = \omega \sqrt{1 - \frac{1}{4} K^2 / \omega^2}$





for now